

```
> restart;
with(PDEtools):
with(plots):
with(LinearAlgebra):
Digits := 14:
```

Boundary value problem for ODEs

Solution using `dsolve`

```
> ode := x^2*diff(u(x),x,x)+x*diff(u(x),x)+(x^2-1)*u(x);
BCs := u(left)=a,u(right)=b;
a := 1;
b := -1;
left := 1;
right := 10;
```

$$ode := x^2 \left(\frac{d^2}{dx^2} u(x) \right) + x \left(\frac{d}{dx} u(x) \right) + (x^2 - 1) u(x)$$

$$BCs := u(left) = a, u(right) = b$$

$$a := 1$$

$$b := -1$$

$$left := 1$$

$$right := 10$$

(1.1)

```
> sol[exact] := subs(factor(dsolve([ode,BCs])),u(x));
```

```
sol_exact :=
```

(1.2)

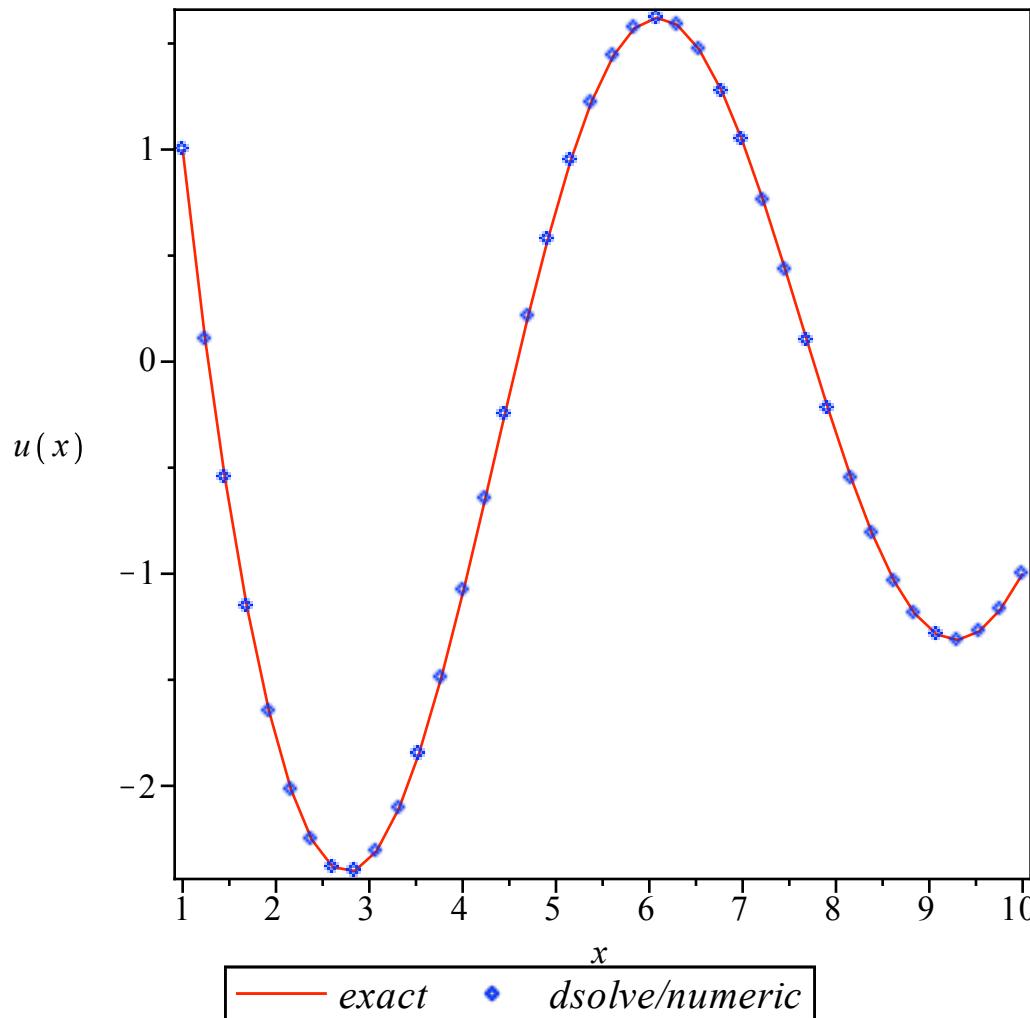
$$-\frac{1}{\text{BesselY}(1, 1) \text{BesselJ}(1, 10) - \text{BesselY}(1, 10) \text{BesselJ}(1, 1)} (\text{BesselJ}(1, x) \text{BesselY}(1, 1) + \text{BesselJ}(1, x) \text{BesselY}(1, 10) - \text{BesselY}(1, x) \text{BesselJ}(1, 1) - \text{BesselY}(1, x) \text{BesselJ}(1, 10))$$

```
> sol[dsolve.numeric] := subs(dsolve([ode,BCs],numeric,output=listprocedure),u(x));
sol_dsolve_numeric := proc(x) ... end proc
```

(1.3)

```
> plot([sol[exact](x),sol[dsolve.numeric](x)],x=left..right,axes=boxed,numpoints=40,
adaptive=false,style=[line,point],color=[red,blue],legend=[exact,`dsolve/numeric`],labels=
```

```
[x,u(x)]) ;
```



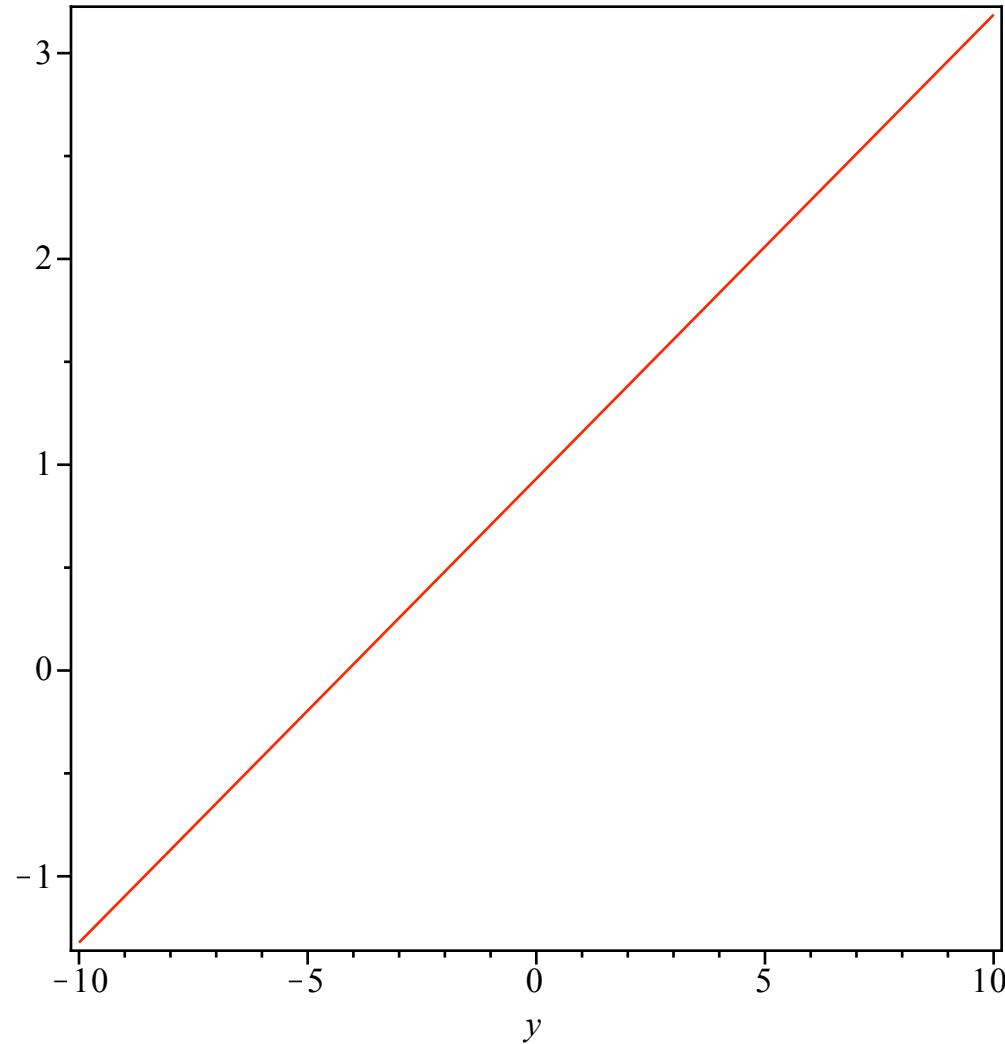
► Solution using the shooting method

```
> F := proc(y)
  local ICs;
  if (type(y,numeric)) then
    ICs := u(left)=a,D(u)(left)=y:
```

```

        dsolve([ode,ICs],numeric,output=Array([right]))[2][1][1,2]:
else:
    'procname'(args):
fi:
end proc:
> plot(F(y)-b,y=-10..10,axes=boxed);

```



```

> y_sol := fsolve(F(y)-b);
y_sol := -4.1343709721299

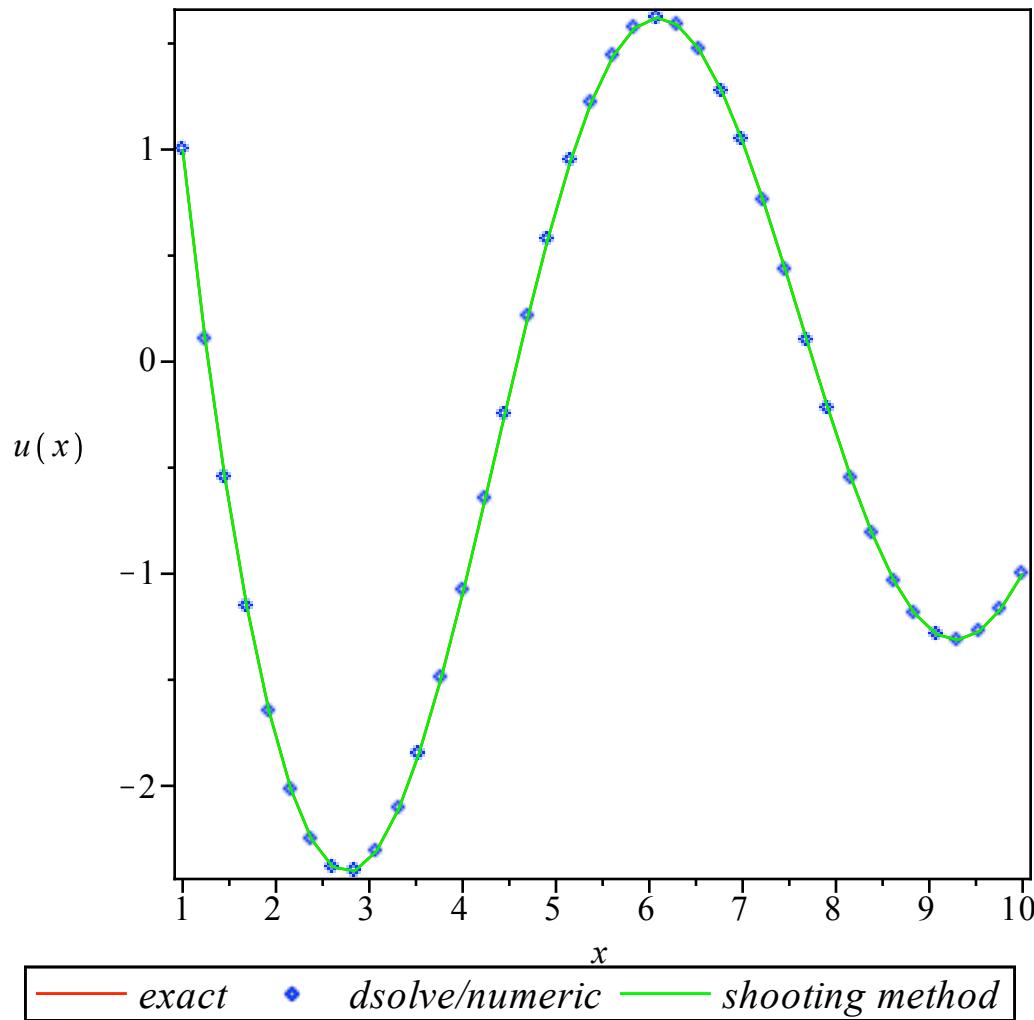
```

(2.1)

```
> ICs := u(left)=a,D(u)(left)=y_sol;
sol[shooting] := subs(dsolve([ode,ICs],numeric,output=listprocedure),u(x));
solshooting := proc(x) ... end proc
```

(2.2)

```
> plot([sol[exact](x),sol[dsolve.numeric](x),sol[shooting](x)],x=left..right,axes=boxed,
numpoints=40,adaptive=false,style=[line,point,line],thickness=[1,0,0],color=[red,blue,
green],legend=[exact,'dsolve/numeric','shooting method'],labels=[x,u(x)]);
```



Solution using matrix methods for linear problems

```
> GenerateStencil := proc(F,N,{orientation:=center,stepsize:=h,showorder:=true,showerror:=false})
    local vars, f, ii, Degree, stencil, Error, unknowns, Indets, ans, Phi, r, n, phi;

    Phi := convert(F,D);
    vars := op(Phi);
    n := PDEtools[difforder](Phi);
    f := op(1,op(0,Phi));
    if (nops([vars])<>1) then:
        r := op(1,op(0,op(0,Phi)));
    else:
        r := 1;
    fi;
    phi := f(vars);
    if (orientation=center) then:
        if (type(N,odd)) then:
            ii := [seq(i,i=-(N-1)/2..(N-1)/2)];
        else:
            ii := [seq(i,i=-(N-1)..(N-1),2)];
        fi;
    elif (orientation=left) then:
        ii := [seq(i,i=-N+1..0)];
    elif (orientation=right) then:
        ii := [seq(i,i=0..N-1)];
    fi;
    stencil := add(a[ii[i]]*subsop(r=op(r,phi)+ii[i]*stepsize,phi),i=1..N);
    Error := D[r$\n](f)(vars) - stencil;
    Error := convert(series(Error,stepsize,N),polynom);
    unknowns := {seq(a[ii[i]],i=1..N)};
    Indets := indets(Error) minus {vars} minus unknowns minus {stepsize};
    Error := collect(Error,Indets,'distributed');
    ans := solve({coeffs(Error,Indets)},unknowns);
    if (ans=NULL) then:
        print(`Failure: try increasing the number of points in the stencil`);
        return NULL;
    fi;
    stencil := subs(ans,stencil);
    Error := convert(series(`leadterm`(D[r$\n](f)(vars) - stencil),stepsize,N+20),polynom);
    Degree := degree(Error,stepsize);
```

```

if (showorder) then:
    print(cat(`This stencil is of order `,Degree));
fi;
if (showerror) then:
    print(cat(`This leading order term in the error is `,Error));
fi;
convert(D[r$n](f)(vars) = stencil,diff);

end proc;

```

> substencil[1] := GenerateStencil(diff(u(x),x),2);
substencil[2] := GenerateStencil(diff(u(x),x,x),3);

This stencil is of order 2

$$substencil_1 := \frac{d}{dx} u(x) = -\frac{1}{2} \frac{u(x-h)}{h} + \frac{1}{2} \frac{u(x+h)}{h}$$

This stencil is of order 2

$$substencil_2 := \frac{d^2}{dx^2} u(x) = \frac{u(x-h)}{h^2} - \frac{2u(x)}{h^2} + \frac{u(x+h)}{h^2} \quad (3.1)$$

> stencil := subs(substencil[2],substencil[1],ode);

$$stencil := x^2 \left(\frac{u(x-h)}{h^2} - \frac{2u(x)}{h^2} + \frac{u(x+h)}{h^2} \right) + x \left(-\frac{1}{2} \frac{u(x-h)}{h} + \frac{1}{2} \frac{u(x+h)}{h} \right) + (x^2 - 1) u(x) \quad (3.2)$$

> stencil := subs(u(x-h)=u[i-1],u(x)=u[i],u(x+h)=u[i+1],x=x[i],stencil);

$$stencil := x_i^2 \left(\frac{u_{i-1}}{h^2} - \frac{2u_i}{h^2} + \frac{u_{i+1}}{h^2} \right) + x_i \left(-\frac{1}{2} \frac{u_{i-1}}{h} + \frac{1}{2} \frac{u_{i+1}}{h} \right) + (x_i^2 - 1) u_i \quad (3.3)$$

> stencil := unapply(stencil,u,x,i,h);

$$stencil := (u, x, i, h) \rightarrow x_i^2 \left(\frac{u_{i-1}}{h^2} - \frac{2u_i}{h^2} + \frac{u_{i+1}}{h^2} \right) + x_i \left(-\frac{1}{2} \frac{u_{i-1}}{h} + \frac{1}{2} \frac{u_{i+1}}{h} \right) + (x_i^2 - 1) u_i \quad (3.4)$$

```

> M := 4;
a := 'a';
b := 'b';
u[0] := a;
u[M+1] := b;
sys := Vector([seq(stencil(u,x,i,h),i=1..M)]);
GenerateMatrix(convert(sys,list),[seq(u[i],i=1..M)]);
u := 'u';

```

$$M := 4$$

$$u_0 := a$$

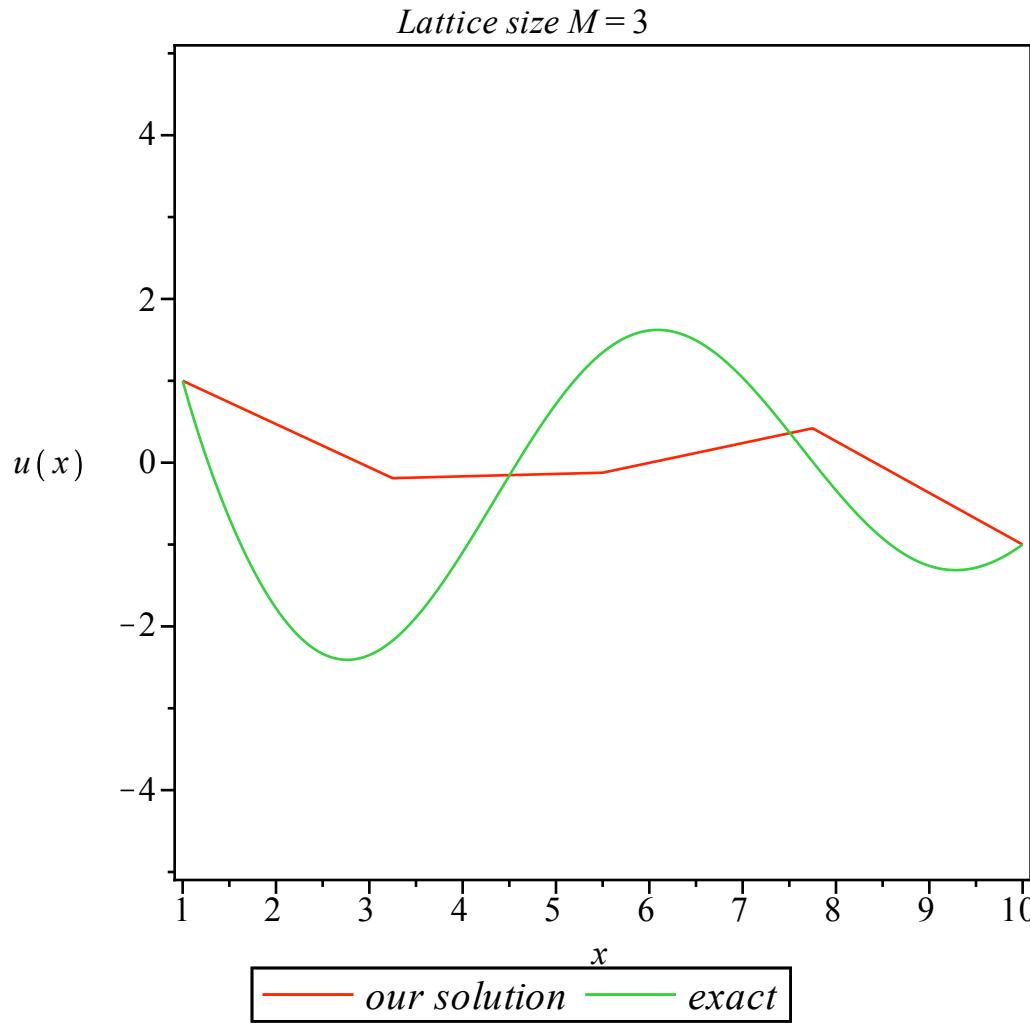
$$u_5 := b$$

$$sys := \begin{bmatrix} x_1^2 \left(\frac{a}{h^2} - \frac{2u_1}{h^2} + \frac{u_2}{h^2} \right) + x_1 \left(-\frac{1}{2} \frac{a}{h} + \frac{1}{2} \frac{u_2}{h} \right) + (x_1^2 - 1) u_1 \\ x_2^2 \left(\frac{u_1}{h^2} - \frac{2u_2}{h^2} + \frac{u_3}{h^2} \right) + x_2 \left(-\frac{1}{2} \frac{u_1}{h} + \frac{1}{2} \frac{u_3}{h} \right) + (x_2^2 - 1) u_2 \\ x_3^2 \left(\frac{u_2}{h^2} - \frac{2u_3}{h^2} + \frac{u_4}{h^2} \right) + x_3 \left(-\frac{1}{2} \frac{u_2}{h} + \frac{1}{2} \frac{u_4}{h} \right) + (x_3^2 - 1) u_3 \\ x_4^2 \left(\frac{u_3}{h^2} - \frac{2u_4}{h^2} + \frac{b}{h^2} \right) + x_4 \left(-\frac{1}{2} \frac{u_3}{h} + \frac{1}{2} \frac{b}{h} \right) + (x_4^2 - 1) u_4 \end{bmatrix}$$

$$\begin{bmatrix} x_1^2 - 1 - \frac{2x_1^2}{h^2} & \frac{1}{2} \frac{x_1}{h} + \frac{x_1^2}{h^2} & 0 & 0 \\ -\frac{1}{2} \frac{x_2}{h} + \frac{x_2^2}{h^2} & x_2^2 - 1 - \frac{2x_2^2}{h^2} & \frac{x_2^2}{h^2} + \frac{1}{2} \frac{x_2}{h} & 0 \\ 0 & -\frac{1}{2} \frac{x_3}{h} + \frac{x_3^2}{h^2} & x_3^2 - 1 - \frac{2x_3^2}{h^2} & \frac{x_3^2}{h^2} + \frac{1}{2} \frac{x_3}{h} \\ 0 & 0 & -\frac{1}{2} \frac{x_4}{h} + \frac{x_4^2}{h^2} & x_4^2 - 1 - \frac{2x_4^2}{h^2} \end{bmatrix}, \begin{bmatrix} -\frac{x_1^2 a}{h^2} + \frac{1}{2} \frac{x_1 a}{h} \\ 0 \\ 0 \\ -\frac{x_4^2 b}{h^2} - \frac{1}{2} \frac{x_4 b}{h} \end{bmatrix} \quad (3.5)$$

```
> MatrixSolver := proc(M,x_range,a,b)
  local left, right, x, h, u, sys, sol:
  left := lhs(x_range):
  right := rhs(x_range):
  x := Vector([seq(left+i/(M+1)*(right-left), i=1..M)], datatype=float[8]):
  h := x[2]-x[1];
```

```
u[0] := a;
u[M+1] := b;
sys := Vector([seq(stencil(u,x,i,h), i=1..M)]);
sol := LinearSolve(GenerateMatrix(convert(sys, list), [seq(u[i], i=1..M)]));
sol := convert(Matrix([x,sol]), listlist);
sol := [[left,a], op(sol), [right,b]]:
end proc:
> p := 'p':
M := 'M':
for i from 3 to 35 do:
p[i] := plot([MatrixSolver(i, left..right, 1, -1), sol[exact](x)], x=left..right, -5..5, axes=boxed, title=typeset(`Lattice size ` , M=i), legend=[`our solution`, `exact`], labels=[x, u(x)]):
od:
display(convert(p, list), insequence=true);
```



► Solution using Newton's method for nonlinear problems

```
> i := 'i':
left := 'left':
right := 'right':
ode := diff(u(x),x,x) + V(u(x))-f(x);
BC := u(left) = a, u(right) = b;
```

$$ode := \frac{d^2}{dx^2} u(x) + V(u(x)) - f(x)$$

$$BC := u(left) = a, u(right) = b$$

(4.1)

```
> stencil := unapply(subs(substencil[2], u(x-h)=u[i-1], u(x)=u[i], u(x+h)=u[i+1], f(x)=f[i],
ode), u, f, i, h);
```

$$stencil := (u, f, i, h) \rightarrow \frac{u_{i-1}}{h^2} - \frac{2u_i}{h^2} + \frac{u_{i+1}}{h^2} + V(u_i) - f_i$$

(4.2)

```
> NonlinearSolver := proc(M,x_range,a,b)
local left, right, x, h, u, sys, sol, F, guess:
left := lhs(x_range):
right := rhs(x_range):
x := Vector([seq(left+i/(M+1)*(right-left), i=1..M)], datatype=float[8]):
h := x[2]-x[1];
F := map(u->f(u), x);
guess := map(u->a + (b-a)*(u-left)/(right-left), x):
u[0] := a;
u[M+1] := b;
sys := [seq(stencil(u, x, i, h), i=1..M)]:
sol := Vector(Newton[vector](sys, [seq(u[i], i=1..M)], guess, 1e-14)):
[[left, a], op(convert(Matrix([x, sol]), listlist)), [right, b]]:
end proc:
```

```
Newton[vector] := proc(Sys, Vars, guess, eps)
local N, vars, i, sys, linearization, linear_sys,
A, b, X, CONTINUE, maxsteps, delta, Subs, d:
N := nops(Sys):
vars := convert(Vars, list):
for i from 1 to N do:
if (type(Sys[i], equation)) then:
    sys[i] := (lhs-rhs)(Sys[i]):
else:
    sys[i] := Sys[i]:
fi;
od;
sys := convert(sys, list);
linearization := map(u->u=u+epsilon*d[u], vars);
linear_sys := map(u->subs(epsilon=1, convert(series(u, epsilon, 2), polynom)), subs(linearization, sys));
```

```

A,b := LinearAlgebra[GenerateMatrix](linear_sys,map(u->d[u],vars));
Subs := seq(vars[i]=q[i],i=1..N);
A := unapply(subs(Subs,A),q);
b := unapply(subs(Subs,b),q);
X[0] := evalf(Vector(guess));
maxsteps := 50;
CONTINUE := true;

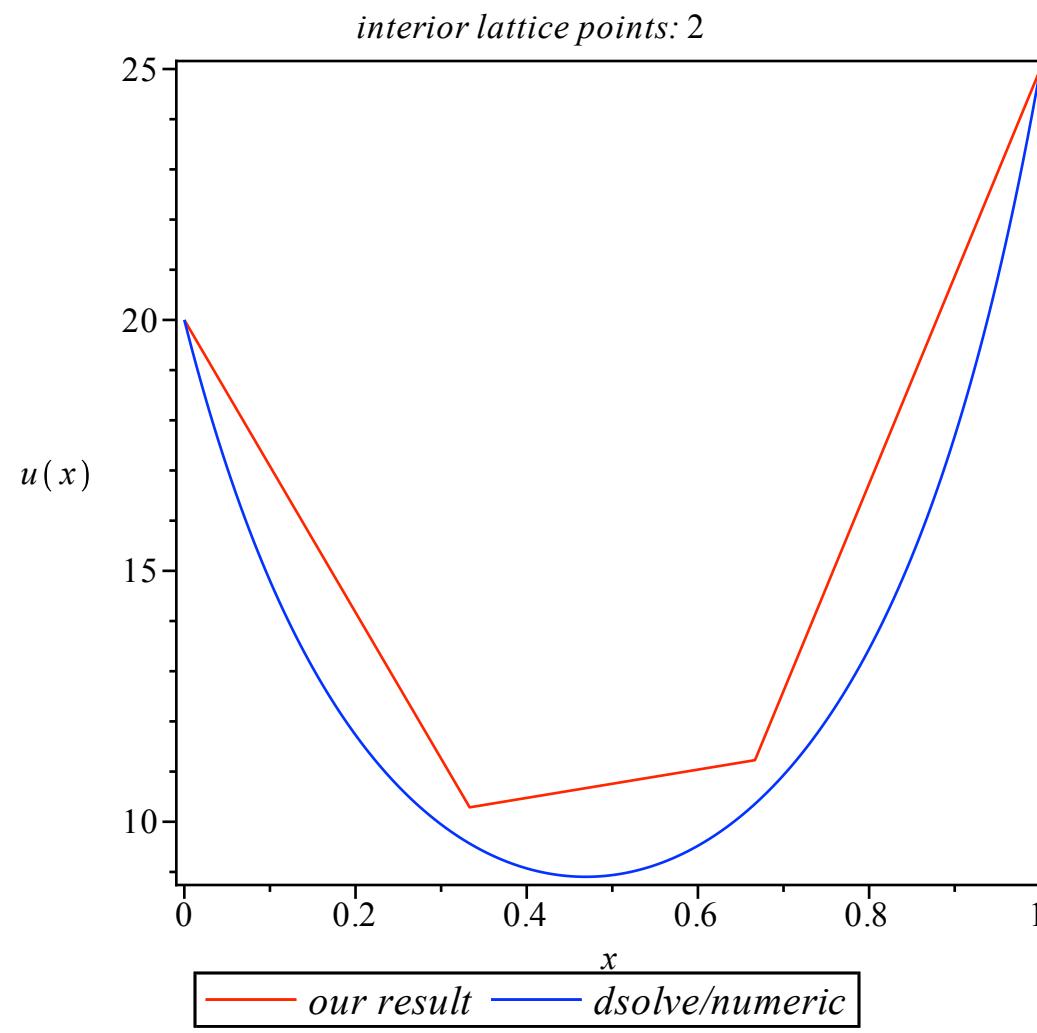
for i from 1 to maxsteps while (CONTINUE) do:
    X[i] := LinearAlgebra[LinearSolve](evalf(A(X[i-1])),evalf(b(X[i-1])))+X[i-1];
    delta := X[i]-X[i-1];
    delta := sqrt(delta^%T.delta)/N;
    if (delta<eps) then CONTINUE := false fi;
od;

if (CONTINUE) then:
    return `maximum number of iterations exceeded`;
else:
    return convert(X[i-1],list);
fi;

end proc;
> p := 'p':
f := x -> -x^3;
V := u -> u*(1-u);
left := 0;
right := 1;
a := 20;
b := 25;

sol[dsolve.numeric] := subs(dsolve([ode,BCs],numeric,output=listprocedure),u(x));
for M from 2 to 20 do:
p[M] := plot([NonlinearSolver(M,left..right,a,b),sol[dsolve.numeric](x)],x=left..right,
labels=[x,u(x)],legend=[`our result`,`dsolve/numeric`],axes=boxed,title=typeset(`interior
lattice points: `,M),color=[red,blue]);
od;
display(convert(p,list),insequence=true);
                                b := 25
soldsolve.numeric := proc(x) ... end proc

```



▼ Relaxation methods

Under construction...